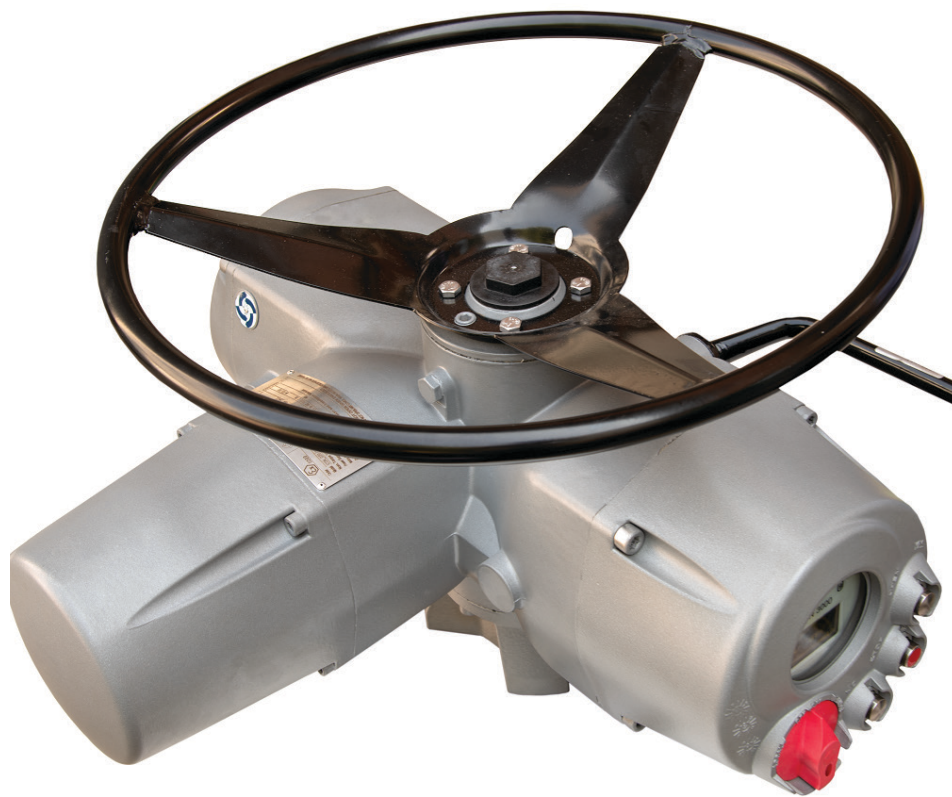


# Biffi ICON3000

## Advanced Maintenance Instructions



**Revision Details**

| Rev. | Date       | Description                                | Prepared | Checked | Approved |
|------|------------|--|----------|---------|----------|
| 1    | March 2021 | General update (Migration to new template) |          |         |          |
| 0    | 04-10-2018 |  | A. B     |         | L. V     |

# Table of Contents

## Section 1: Introduction

|                   |   |
|-------------------|---|
| Introduction..... | 1 |
|-------------------|---|

## Section 2: Reserved Passwords

|                         |   |
|-------------------------|---|
| Reserved Passwords..... | 2 |
|-------------------------|---|

## Section 3: Restricted Menu Routines

|  |    |
|--|----|
| 3.1 Torque Stop Zone.....                          | 5  |
| 3.2 Speed Bypass .....                             | 5  |
| 3.3 Voltage Span.....                              | 6  |
| 3.4 1 P.man .....                                  | 6  |
| 3.5 HW Config .....                                | 6  |
| 3.6 Positioner.....                                | 7  |
| 3.7 Request.....                                   | 7  |
| 3.8 Fail Safe .....                                | 7  |
| 3.9 Bus An-Out.....                                | 7  |
| 3.10 Direction Test.....                           | 7  |
| 3.11 Card Ain/Aout .....                           | 8  |
| 3.12 Bluetooth Extension Antenna or Bluetooth..... | 8  |
| 3.13 IRDA.....                                     | 8  |
| 3.14 Bus Protocol .....                            | 9  |
| 3.15 PID.....                                      | 9  |
| 3.16 Reserved Routines.....                        | 9  |
| 3.16.1 SW Type.....                                | 9  |
| 3.16.2 Term Board .....                            | 9  |
| 3.16.3 Additional Var. ....                        | 9  |
| 3.16.4 Reversal Delay.....                         | 11 |
| 3.16.5 Backlight.....                              | 11 |
| 3.16.6 4 - 20 mA Config.....                       | 12 |
| 3.16.7 Current Sensor.....                         | 12 |
| 3.16.8 Torque Sensor .....                         | 13 |
| 3.16.9 Speed Band.....                             | 13 |
| 3.16.10 Base Temp. Ref.....                        | 13 |
| 3.16.11 LCD Temp. Ref.....                         | 13 |
| 3.16.12 TERM Temp. Ref. ....                       | 13 |
| 3.16.13 Torque Function.....                       | 13 |
| 3.16.14 Interlock Mode .....                       | 13 |
| 3.16.15 Sleep.....                                 | 13 |
| 3.16.16 MR in Sleep .....                          | 13 |
| 3.16.17 New FW.....                                | 13 |
| 3.16.18 Serial CMD .....                           | 14 |
| 3.16.19 Loc/Rem .....                              | 14 |
| 3.16.20 Bluetooth Code.....                        | 14 |
| 3.16.21 EFS Duty .....                             | 14 |
| 3.16.22 Spring Action.....                         | 14 |
| 3.16.23 EFS EL.CMD.....                            | 14 |
| 3.16.24 ESD Input Mode .....                       | 14 |
| 3.16.25 CMD-filter.....                            | 14 |
| 3.16.26 ESD/INT-filter .....                       | 14 |

|  |    |
|--|----|
| <b>Section 4: Alarm "Configuration n°"</b>           |    |
| 4.1 Object List of ICON3000.....                     | 16 |
| <b>Section 5: Alarm "Hardware n°"</b>                |    |
| <b>Section 6: Terminal Board Types</b>               |    |
| 6.1 Terminal Board Adaptor (TBA) Card.....           | 35 |
| <b>Section 7: Configuration</b>                      |    |
| Configuration.....                                   | 36 |
| <b>Section 8: Test Point and Connector Base Card</b> |    |
| Test Point and Connector Base Card.....              | 39 |
| <b>Section 9: Firmware Of DE9425 HW REV ≥ 00B</b>    |    |
| Firmware Of DE9425 HW REV ≥ 00B.....                 | 40 |

# Section 1: Introduction

This manual should be used in conjunction with the Installation, Operation and Maintenance Manual (IOM) of the ICON3000.

This manual supplies an additional set of instructions for service and troubleshooting and describes the parameters available in the RESTRICTED MENU.

The routines contained within the RESTRICTED menu can significantly modify the functionality of the actuator; therefore, access to and utilization of the RESTRICTED menu should be limited to only trained and authorized technicians.

If any parameter in the RESTRICTED menu is changed, power must be cycled on the actuator for the changes to take effect.

## Section 2: Reserved Passwords

The VIEW and SETUP features available through the Local Operator Interface allows the user to set actuator characteristics according to the needs of the process and to view diagnostic messages and status.

To enter the SETUP menu a password is required. Three levels of password are available:

1. **Password level 0:** This is the "user" password and consists of 4 alphanumeric characters. The actuator is supplied with the password "0000" (four zeros) from the factory. The user can change this factory password as described in the ICON3000 IOM.
2. **Password level 1:** This password allows the user all of the functionality afforded by Level 0, but also allows the NAMEPLATE routine to be entered and changed. Nameplate data is normally entered in the factory. The Level 1 password (not "0000") is entered in the same fashion as Level 0.
3. **Password level 2:** This password offers all the functionality of Levels 0 and 1, and also offers entry into the RESTRICTED routine of the ACTUATOR SETUP menu. Special routines can be found within the RESTRICTED routine that are generally used to enable and disable hardware and software modules, and calibrate the ICON3000's sensors. There is a special procedure for entering the Level 2 password, which is as follows:
  - Enter VIEW and SETUP menu as described in the IOM of the actuator.
  - Select language.
  - Select SETUP mode.
  - Enter password:
    - Select the 1<sup>st</sup> character of password, and then press YES.
    - Select the 2<sup>nd</sup> character of password, and then press YES.
    - Select the 3<sup>rd</sup> character of password, and then press YES.
    - Select the 4<sup>th</sup> character of password, and then press YES and keep this push-button pressed down until the display shows the message "PASSWORD CORRECT."  
The button must be kept pushed down for approximately 10 seconds for the password to be accepted.
  - Confirm SETUP mode.
  - Confirm ACTUATOR SETUP.
  - Scroll the ACTUATOR SETUP routines until the display shows the message "RESTRICTED."  
Press YES to enter.
  - View or change the restricted parameter(s), and then EXIT from the menu.

Upon having changed any parameter in the RESTRICTED menu, actuator power must be cycled in order for the changes to take effect.

Contact Emerson Lifecycle Services to request access to the Level 1 and Level 2 passwords.

The list below shows the available routines in the ACTUATOR SETUP menu:

- Stroke limits
- Torque set up
- PST set up\*
- ESD set up\*
- EFS/PST\*
- Remote controls
- Local controls
- Output relays
- Positioner\*
- Fail Safe\*
- Out 4 - 20 mA\*
- Interlock\*
- 2 speed timer
- Bus\*
- Miscellaneous
- Restricted
- Reserved

The routines with marked with an asterisk (\*) are present only if the relevant electronic cards are present. Should the bus interface be LonWorks, then the BUS routine will display as "FDI CONTROL." The RESTRICTED menu routine will only appear if the Level 2 password is entered.

## Section 3: Restricted Menu Routines

Within the RESTRICTED menu, certain routines are grouped into RESTRICTED and RESERVED categories. To access the RESERVED routines, scroll through each of the RESTRICTED routines and when the menu displays EXIT OK, press the NO push-button. Each routine is listed as follows:

### Restricted Routines

- Torque stop zone
- Speed bypass
- Voltage span
- 1 P.man
- HW config.
- Positioner
- Request
- Fail Safe
- Bus An-out
- Direction test
- Card Ain/Aout
- BLT ext. antenna or Bluetooth
- IrDA
- Bus protocol
- PID

#### Reserved Routines

- SW type
- Term. board
- Additional var.
- Reversal delay
- Backlight
- 4 - 20 mA config.
- Current sensor
- Torque sensor
- Speed band
- Base temp. ref.
- LCD temp. ref.
- Term. temp. ref.
- Torque function
- Interlock mode
- Sleep mode
- MR in sleep
- New FW
- Serial cmd
- Loc/Rem
- Bluetooth code
- EFS duty
- Spring action
- EFS. EL. CMD
- ESD input mode
- CMd filter
- ESD-INT filter

## 3.1 Torque Stop Zone

If the torque limit is reached in the position interval “0 to torque stop zone” and “100-torque stop zone to 100” and opening or closing stroke limits are set by torque, then the ICON3000 considers the reached position as “end of travel.” If the torque limit is reached at a position between “torque stop zone” and “100-torque stop zone,” then the ICON3000 will generate an alarm. If the torque limit is not reached the warning “wrong stroke limit” is generated. Standard value = 5%.

## 3.2 Speed Bypass

This is the time needed to update the motor speed after receipt of an open or close command. Standard value = normally >1.5 seconds (depends on actuator type).

### 3.3 Voltage Span

This function allows to recalibrate the sensor that measures the main voltage supply. The recalibration procedure is as follows:

Using a multimeter, measure the value of the voltage supply on terminals L1/L2 of the terminal board. On the actuator display, enter the same value measured by the multimeter and then press YES. The new value is accepted only if it is at least 1 V different from the previous value. Pressing YES will not effect any change in voltage sensor calibration if the value indicated on the display is not changed.

### 3.4 1 P.man

This function is also known as "Gear Relaxation," and functions by backing off the motor a small amount at either end of the valve travel. The effect is to reduce compressive stress on the actuator gears and facilitate engagement of the manual override declutch lever. This routine is set in-house. Standard value = DISABLED.

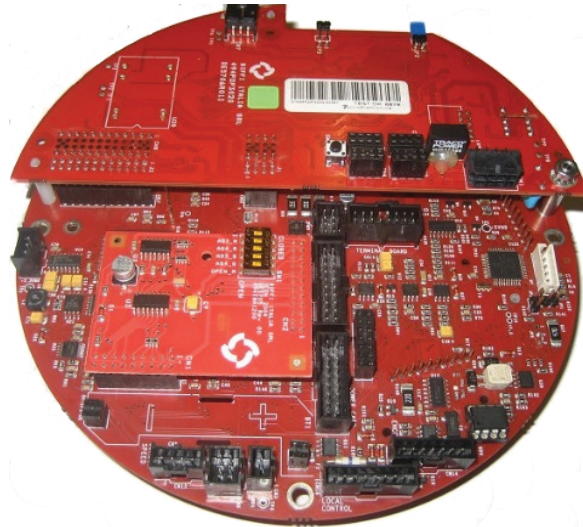
### 3.5 HW Config

This function is used to select the fieldbus control option. The following options can be selected:

- Base (No bus control)
- Lon (Lonworks)
- Mod-bus (Modbus RTU)
- Prof-V0 (Profibus DPV0)
- Mod-m (Modbus RTU)
- FF (Foundation Fieldbus)
- Hart (Hart)
- Prof-V1 (Profibus DPV1)
- Prof-V1r (Profibus DPV1 redundant)
- MOD-Dw (Modbus Dewa)
- Prof-V2 (Profibus DPV2)
- Prof-V2r (Profibus DPV2 redundant)

If the "base" option is set, then a fieldbus interface card is not required. If one of other options is chosen, the ICON3000 base card must be equipped with the appropriate bus interface card. It is also necessary to set the parameter "bus protocol" that sets the type of communication protocol between the base card and the bus interface card. The "BUS" routine appears in the ACTUATOR SETUP menu and the relevant parameters (node address, baud rate, etc.) can be viewed and changed as described in the ICON3000 IOM. If the option LONWORKS is chosen, the "BUS" routine in the ACTUATOR SETUP menu changes to "FDI CONTROL."

Figure 1 Base Card of ICON3000 Equipped with a Bus Card



### 3.6 Positioner

This routine allows the user to enable or disable the positioner function. If the option ENABLED is set, the POSITIONER routine appears in the ACTUATOR SETUP menu and the relevant parameters (dead band, motion inhibit time, etc.) can be viewed and changed as described in the ICON3000 IOM. The type of position request signal (from 4 - 20 mA input or from bus) is set by the routine REQUEST.

### 3.7 Request

This routine allows the user to select the type of position request signal used in the POSITIONER routine. The options available are 4 - 20 mA and BUS. Set BUS. if the positioner will receive the position request from bus interface and set "4 - 20 mA" if the position request signal will be received from the optional analog 4 - 20 mA input/output module (named "Ain/Aout"). The parameter "CARD Ain/Aout" must be set to PRESENT.

### 3.8 Fail Safe

This routine allows the user to enable or disable the fail safe action performed by the actuator in cases of remote control failure via bus or via 4 - 20 mA analog input. If the option ENABLED is chosen, the routine FAIL SAFE appears in the ACTUATOR SETUP menu and the relevant parameters (action and delay) can be viewed and changed as described in the ICON3000 IOM.

### 3.9 Bus An-Out

This parameter is set in-house. The standard value is "TORQUE."

### 3.10 Direction Test

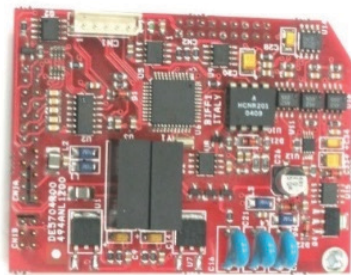
This parameter is used in the ICON3000 in the direction test. If the test fails a SPEED SENSOR alarm is generated. The standard value for ICON3000 is 1.

## 3.11 Card Ain/Aout

This parameter has two options: PRESENT or ABSENT. Set PRESENT if the base card is equipped with the optional 4 - 20 mA input/output card ("Ain/Aout") that provides an analog 4 - 20 mA input and output to the actuator. The routine OUT 4 - 20 mA appears in the ACTUATOR SETUP menu and the relevant parameters (e.g. polarity) can be viewed and changed as described in the ICON3000 IOM. A report message can also be viewed as described in the same IOM.

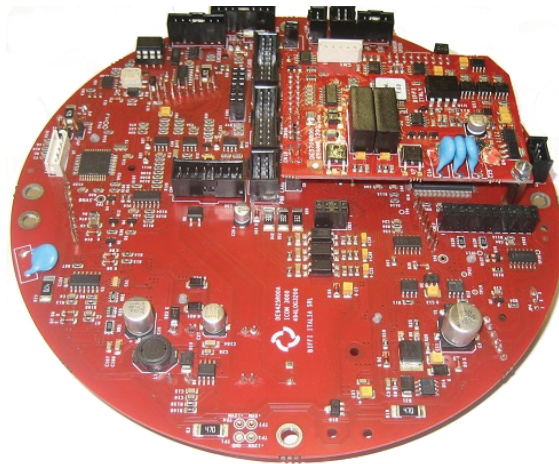
Set the parameter to ABSENT if the terminal board adaptor card (see Section 6.1) has been installed instead of the 4 - 20 mA "Ain/Aout" card. Setting this parameter incorrectly can result in a hardware alarm (refer to the ICON3000 IOM for details on this alarm).

Figure 2 Ain/Aout Card



This optional card is used in place of the Terminal Board Adaptor card when an analog 4 - 20 mA input and output signal is requested.

Figure 3 ICON3000 Base Card Equipped with Ain/Aout Card



## 3.12 Bluetooth Extension Antenna or Bluetooth

This parameter has two options: ENABLED or DISABLED. If the BLUETOOTH parameter is enabled, the RS232 service line on the base card will not be available. The BLUETOOTH parameter needs to be set to DISABLED before using the RS232 service line. Therefore, it is recommended to set BLUETOOTH to DISABLED.

## 3.13 IRDA

This function is not implemented. It is normally set to DISABLED.

## 3.14 Bus Protocol

This parameter allows the user to select the communication protocol between the base card and fieldbus interface card. I20 and I24 are the two available options. Refer to the relevant ICON3000 bus protocol manual to correctly set this parameter.

## 3.15 PID

This function is not implemented. It is normally set to DISABLED.

## 3.16 Reserved Routines

### 3.16.1 SW Type

This routine must be set to "ICON."

### 3.16.2 Term Board

This routine must be set to "I24\_V4."

### 3.16.3 Additional Var.

The standard value is "MASK" and the following data can be viewed:

- Output torque
- Motor speed
- Main voltage
- Current
- Temperature
- Time
- Date
- Alarm
- Warning
- Ktemp
- Mot temp
- Term temp
- Log status
- Wireless report
- Node report\*
- FDI report\*
- Base report
- Term report
- Ain/Aout report\*
- EFS report\*

The data with \* are present only if the relevant modules are present.

With the option VIEW, additional data useful for maintenance can be viewed:

- Battery Value: value in volt of the battery
- Remote Command: status of the DIs => bit0: not used, bit1: ESD, bit2: Open, bit3: Close, bit4: Stop, bit5: Man, bit6: Int\_CL, bit7: Int\_OP
- Encoder Abs Position: 0 to 2196479
- Encoder Status: bit0 = CCW, bit7 = calibrated, bit8 = communication error, bit9 = CW/CCW wrong communication
- Encoder wheel 1: 0 to 2047
- Encoder wheel 2: 0 to 2047
- Encoder wheel 3: 0 to 2047
- Encoder limit 0%
- Encoder limit 100%
- Encoder Error: error counter (communication between Base card and Encoder)
- Counter: position %
- Pic Word 1: Status => (bit0: wake up H8, bit2: encoder OK, bit10: Position OK, bit11: Low bat, bit12: 24 V\_ext\_present, bit13: 13 V dc present, bit 14: CRC PIC OK, bit15: calibration in progress)
- Pic Word 2: Push-buttons/Selector => bit0: remote, bit1: Local, bit2: stop, bit3: close, bit4: open, bit5: not configured as ICON
- Pic Word 3: encoder status => bit0 = CCW, bit7 = calibrated, bit8 = communication error, bit9 = CW/CCW wrong communication
- Pic Word 4: encoder error counter (communication between Base card and Encoder)
- Pic Word 5: reserved
- Pic Word 6: reserved
- Pic Word 7: reserved
- Pic Word 8: reserved
- Pic Word 9: reserved
- Pic Word 10: reserved
- Pic Word 11: reserved
- Pic Word 12: reserved
- Pic Word 13: reserved
- Pic Word 14: reserved
- Pic Word 15: configuration => bit0: battery present, bit1: CCW
- Pic Word 16: reserved
- Pic Port A: status of the pic port A
- Pic Port B: status of the pic port B
- Pic Port C: status of the pic port C
- Pic Port D: status of the pic port D
- Pic Port E: status of the pic port E
- Pic AN0: PIC analog input (battery value in bit)

- Port 4 an0: not used
- Port 4 an1: not used
- Port 4 an2: not used
- Port 4 an3: main voltage in bits
- Port 4 an4: motor current in bits
- Port 4 an5: terminal board type in bits
- Port 4 an6: auxiliary contact of K1 contactor in bits
- Port 4 an7: current range out in bits
- Port 9 an0: auxiliary contact of K2 contactor in bits
- Port 9 an1: status of Bluetooth module in bits
- Port 9 an2: reserved. Not used for ICON3000
- Port 9 an3: motor thermostat in bits
- Port 9 an4: motor temperature in bits
- Port 9 an5: not used
- Port 9 an6: heater cmd in bits
- Port 9 an7: backlight cmd in bits

### 3.16.4 Reversal Delay

This function sets the delay implemented as part of the instantaneous reversal feature (i.e. reverse motor rotation). Standard value is 1.1 seconds.

### 3.16.5 Backlight

The standard value is AUTO. The backlight of display automatically switches off 2 minutes after the last operation with the local operator interface. This option increases the life of the display since the backlight is powered only when using the local operator interface.

With the option "ON," the backlight of the display is always powered. Use this option only when absolutely necessary.

### 3.16.6 4 - 20 mA Config

This routine is used to calibrate the 4 - 20 mA input and outputs. This is normally done in-house. Should it be necessary to recalibrate the 4 - 20 mA input and output, this needs to be conducted in two steps.

Reconfigure the limits of the A/D and D/A converters of the base card as follows:

- Enter VIEW and SETUP menu as described in the ICON3000 IOM.
- Select the language.
- Select SETUP mode.
- Enter the Level 2 password.
- Select ACTUATOR SETUP.
- Scroll the list of routines and press YES when the message displayed is “RESTRICTED.”
- Press YES to scroll the list of “RESTRICTED” routines and press NO when the message displayed is “EXIT OK?”.
- Press YES until the message displayed is “4 - 20 mA CONFIG. CHANGE?”
- Press YES to enter the “4 - 20 mA CONFIG.” routine. The message displayed will be “READ OK?”.
- Press YES to view or change the configured values corresponding to I = 4 mA (from 0 to 2000), I = 20 mA (from 2000 to 4095), O = 4 mA (from 0 to 2000), O = 20 mA (from 2000 to 4095). Press YES to confirm and skip to next step or press NO to change. Values out of range cause a CONFIGURATION alarm.
- Or press NO to skip to “SETUP OK?”.
- When the message displayed is “SETUP OK?” press NO to exit or press YES to recalibrate:
  - Connect a 4 - 20 mA current generator to terminals B8/B9 and a multimeter in mA to terminals C10/B7 in accordance with the electrical diagrams.
  - The message displayed is “I = 4 mA=xxxx.”
  - Set the current generator to 4 mA. The displayed value should be from 0 to 2000. Press YES.
  - Set the current generator to 20 mA. The displayed value should be from 2000 to 4095. Press YES.
  - Press NO until the multimeter indicates 4 mA. The displayed value should be from 0 to 2000. Press YES.
  - Press NO until the multimeter indicates 20 mA. The displayed value should be from 0 to 2000. Press YES.
  - Exit from the configuration menu.

### 3.16.7 Current Sensor

This routine includes the calibration values of the current sensor. Calibration of the current sensor is done in-house. Enter the routine only if a new setting is required. There are two options available: READ and SETUP. In READ mode the operator can view and change the values corresponding to currents 2 A, 3.5 A, 7 A, 15 A, and 30 A via the local operator interface. Do not enter SETUP mode. When the message displayed is “CURRENT SENSOR CHANGE?” press NO to skip to next routine or press YES to enter. The display will show the message “READ OK?” Press YES to view or change the values. If the NO push-button is pressed the message displayed will be “SETUP OK?” Press NO to exit.

### 3.16.8 Torque Sensor

This routine is used in-house to set torque sensor parameters. Do not enter into this routine; if this occurs, press NO when the message TORQUE SENSOR CHANGE? is displayed.

### 3.16.9 Speed Band

The standard value is 10. The value is automatically adjusted as a function of the number of motor poles stated in the motor data section of the NAMEPLATE menu.

### 3.16.10 Base Temp. Ref.

The standard value is 2 °C. When the temperature inside the electronics compartment is less than the above value, the heater of the base card is powered.

### 3.16.11 LCD Temp. Ref.

The standard value is -5 °C. When the temperature inside the terminal board compartment is less than the above value, the heater of the LCD display is powered.

### 3.16.12 TERM Temp. Ref.

The standard value is 0 °C. When the temperature inside the terminal board compartment is less than the above value, the heater on the terminal board cards is switched on.

### 3.16.13 Torque Function

This parameter is normally set to "STANDARD."

### 3.16.14 Interlock Mode

This parameter is normally set to "STANDARD" and INTERLOCK function is available. If the INTERLOCK MODE is set in "ADVANCED" the ICON300 use the Interlock input as PST commands. INTERLOCK OPEN becomes command to carry out PST in open direction. INTERLOCK CLOSE becomes command to carry out PST (Partial Stroke Test) in close direction. PST function are performed only if the actuator is fully open or closed.

### 3.16.15 Sleep

This parameter is normally set to "DISABLED." Use the option to enable SLEEP function. Refer to the ICON3000 Sleep Mode manual for a detailed description of this function.

### 3.16.16 MR in Sleep

This parameter is normally set to "OFF." Use this option to set MR to OFF or ON when the SLEEP function is enabled. Refer to the ICON3000 Sleep Mode manual for a detailed description of this function.

### 3.16.17 New FW

This parameter is normally set to "DISABLED." Use the option ENABLED only if the base card firmware must be updated. Set the back to DISABLED after upgrading the firmware. Refer to the appropriate instructions relevant to firmware upgrades.

### 3.16.18 Serial CMD

This parameter is normally set to “DISABLED.” Use this option to enable OP/CL/STOP command from Bluetooth, RS232 interface.

### 3.16.19 Loc/Rem

This parameter is normally set to “DISABLED.” Use this option to enable local OP/CL/STOP commands also when the local selector is in REMOTE (LOC+REM).

### 3.16.20 Bluetooth Code

This parameter is normally set to “S/N.” Use this option to select Bluetooth code between “S/N” = actuator serial number and “V/TAG” = valve tag.

### 3.16.21 EFS Duty

Reserved. Not used by ICON3000.

### 3.16.22 Spring Action

Reserved. Not used by ICON3000.

### 3.16.23 EFS EL.CMD

Reserved. Not used by ICON3000.

### 3.16.24 ESD Input Mode

Reserved. Not used by ICON3000.

### 3.16.25 CMD-filter

This parameter is normally set to 1. The maximum value is 32. Use this option to set the filter level of OP/CL/ST commands.

Set the above parameter to 100 if a fast reaction is required in response to open and close commands.

The setting causes the following changes:

- Control mode in local and remote changes to “push to run.”
- Filtering reduced to the minimum.

### 3.16.26 ESD/INT-filter

This parameter is normally set to 1. The maximum value is 32. Use this option to set the filter level of ESD/INT commands.

## Section 4: Alarm "Configuration n°"

If the checksum of the EEPROM memory containing the data of ICON3000 settings is wrong, exit the alarm "CONFIGURATION n°" (refer to the ICON3000 IOM).

Every configuration parameter is called "OBJECT or OBJ" and is characterized by an "OBJ number." The number "n°" indicates the number of the OBJ that is out of range.

To clear the configuration alarm, it is necessary to set the correct value using the VIEW and SETUP features as described in the ICON3000 IOM.

If the alarm message is "CONFIGURATION OBJ 9999," only one of the actuator parameters needs to be changed. For example: enter the SETUP menu, then ACTUATOR SETUP, then TORQUE SETUP, then and increase or decrease the closing torque by 1%. When the alarm message disappears, reenter the SETUP menu, then ACTUATOR SETUP, then TORQUE SETUP, and then set the previous value.

If the alarm message is "CONFIGURATION OBJ 720 or 721 or 722 or 723," proceed as follows:

- Repower the actuator and observe the first message of the display. If the ICON3000 base card is equipped with the "Ain/Aout" optional card, check the following parameters in the "RESTRICTED" menu routines:
  - Term board: should be set to "124 V4"
  - Card Ain/Aout: should be set to "PRESENT"

If the settings are wrong, enter the correct values and then proceed to cycle power on the actuator.

In the following table is the list of the Objects (or parameters). The OBJECTS are sorted according to the actuator menu. Every line of the table gives a complete description of the Object by means of "OBJ n°," "normal value," "function," and "description and ranges."

## 4.1 Object List of ICON3000

Table 1. Stroke Limits and Torque Setup

| Obj n° | Value | Actuator Setup           |                  |
|--------|-------|--------------------------|------------------|
|        |       | Function                 | Description      |
| 102    | CW    | Close direction          | CW, CCW          |
| 100    | Off   | Close limit type         | Torque, position |
| 101    | Off   | Open limit type          | Torque, position |
| 506    | 70    | Closing torque           | From 40 to 100%  |
| 505    | 75    | Opening torque           | From 40 to 100%  |
| 510    | 60    | Breakout in closing      | From 40 to 100%  |
| 511    | 40    | Peak run in closing      | From 40 to 100%  |
| 512    | 80    | Ending in closing        | From 40 to 100%  |
| 513    | 90    | Breakout zone in closing | From 0 to 100%   |
| 514    | 10    | Ending zone in closing   | From 0 to 100%   |
| 515    | 90    | Breakout in opening      | From 40 to 100%  |
| 516    | 40    | Peak run in opening      | From 40 to 100%  |
| 517    | 80    | Ending in opening        | From 40 to 100%  |
| 518    | 20    | Breakout zone in opening | From 0 to 100%   |
| 519    | 80    | Ending zone in opening   | From 0 to 100%   |

Table 2. ESD Setup

| Obj n° | Value                     | Actuator Setup                  |  |
|--------|---------------------------|---------------------------------|--|
|        |                           | Function                        | Description  |
| 600    | Off                       | ESD action                      | Off, close, open, stay put, go to position %               |
| 601    | 50                        | ESD position                    | From 0 to 100  |
| 605    | ESD<thermostat            | ESD and motor thermostat alarm  | ESD<thermostat, ESD>thermostat                             |
| 606    | ESD<local stop            | ESD and torque alarm            | ESD<torque limit, ESD>torque limit                         |
| 607    | ESD<local stop            | ESD and local stop              | ESD<local stop, ESD>local stop                             |
| 608    | ESD<local selector        | ESD and local selector in LOCAL | ESD<local selector, ESD>local selector                     |
| 609    | ESD<local selector in OFF | ESD and local selector in OFF   | ESD<local selector in OFF, ON=ESD>local selector in OFF    |
| 611    | ESD<2 speed timer         | ESD and 2-speed timer           | ESD<2-speed timer, ESD>2-speed timer                       |
| 602    | Present                   | ESD signal type                 | ESD carried out: with signal absent or with signal present |

**Table 3. EFS / PST**

| Obj n° | Value  | Function                              | Actuator Setup  |  |
|--------|--------|---------------------------------------|---|--|
|        |        |                                       | Description   |  |
| 800    | Off    | EFS action in case of voltage failure | On/Off selector to perform safe action if main voltage of actuator fails<br>Not used for ICON3000       |  |
| 801    | Off    | EFS action in case of selector in OFF | On/Off selector to perform safe action if local selector of actuator is in OFF<br>Not used for ICON3000 |  |
| 802    | On     | Auto-reset                            | On/Off selector to re-energize the clutch after the configured time                                     |  |
| 810    | 30     | Reset-delay                           | Time to re-energize the clutch  |  |
| 811    | 360    | PST period                            | Period of PST in days   |  |
| 812    | 12     | PST hour                              | Time of PST in hours  |  |
| 813    | 10     | PST travel                            | Travel of PST in % of stroke  |  |
| 814    | 100    | Max. T-PST%                           | Max. T-PST in % of reference  |  |
| 816    | Manual | PST mode                              | Selector Off/manual/man-auto/auto   |  |
| 817    | 100    | Max. T-RET%                           | Max. T-RET in % of reference  |  |
| 818    | 1      | PST pause                             | Pause time  |  |
| 819    | 100    | Max. OV-TR%                           | Max. over-travel in % of stroke   |  |

**Table 4. Remote and Local Controls**

| Obj n° | Value   | Function            | Actuator Setup  |  |
|--------|---------|---------------------|---|--|
|        |         |                     | Description   |  |
| 121    | Off     | Remote control type | Off, 4 wires latched, 3 wires push to run, 3 wires instant reverse, 2 wires open if signal off, 2 wires open if signal on |  |
| 120    | Latched | Local control type  | Latched, push to run, latched instant reverse, push-to-run relAs5-6   |  |
| 1      | On      | Close led color     | Closed led color=ON=red, OFF=green  |  |
| 2      | Off     | Open led color      | Open led color=ON=red, OFF=green  |  |
| 3      | On      | Alarm led color     | Alarm led color=ON=yellow, OFF=red  |  |
| 30     | Off     | Remote stop type    | Remote stop active if signal is on=make or off=break  |  |

### Output Relays

**Table 5. Monitor Relay**

| Obj n° | Value   | Function                     | Actuator Setup                             |  |
|--------|---------|------------------------------|--|--|
|        |         |                              | Description                                |  |
| 201    | Enabled | Local STOP pressed           | Enabled, disabled                          |  |
| 202    | Enabled | Local OFF                    | Enabled, disabled                          |  |
| 203    | Enabled | ESD - EFS                    | Enabled, disabled<br>Not used for ICON3000 |  |
| 204    | Enabled | Manual operation             | Enabled, disabled                          |  |
| 206    | Enabled | Motor high temperature alarm | Enabled, disabled                          |  |
| 207    | Enabled | High torque alarm            | Enabled, disabled                          |  |
| 208    | Enabled | Jammed valve alarm           | Enabled, disabled                          |  |
| 209    | Enabled | Low battery alarm            | Enabled, disabled                          |  |

Table 6. AS1 Relay

| Obj n° | Value      | Function      | Actuator Setup   |
|--------|------------|---------------|--|
|        |            |               | Description  |
| 220    | Open limit | AS1_condition | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 240    | 20         | AS1 position% | Position% if AS1 condition is position >=% or <=%  |
| 231    | Make       | AS1 contact   | Make, break  |

Table 7. AS2 Relay

| Obj n° | Value       | Function      | Actuator Setup   |
|--------|-------------|---------------|--|
|        |             |               | Description  |
| 221    | Close limit | AS2 condition | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 241    | 20          | AS2 position% | Position% if AS2 condition is position >=% or <=%  |
| 232    | Make        | AS2 contact   | Make, break  |

Table 8. AS3 Relay

| Obj n° | Value      | Function      | Actuator Setup   |
|--------|------------|---------------|--|
|        |            |               | Description  |
| 222    | Open limit | AS3 condition | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 242    | 20         | AS3 position% | Position% if AS3 condition is position >=% or <=%  |
| 233    | Make       | AS3 contact   | Make, break  |

**Table 9. AS4 Relay**

| Obj n° | Value       | Function      | Actuator Setup |  |
|--------|-------------|---------------|----------------|--|
|        |             |               | Description    |  |
| 223    | Close limit | AS4 condition |                | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 243    | 20          | AS4 position% |                | Position% if AS4 condition is position >=% or <=%  |
| 234    | Make        | AS4 contact   |                | Make, break  |

**Table 10. AS5 Relay**

| Obj n° | Value      | Function      | Actuator Setup |  |
|--------|------------|---------------|----------------|--|
|        |            |               | Description    |  |
| 1200   | Open limit | AS5 condition |                | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 1210   | 20         | AS5 position% |                | Position% if AS5 condition is position >=% or <=%  |
| 1220   | Make       | AS5 contact   |                | Make, break  |

**Table 11. AS6 Relay**

| Obj n° | Value      | Function      | Actuator Setup |  |
|--------|------------|---------------|----------------|--|
|        |            |               | Description    |  |
| 1201   | Open limit | AS6 condition |                | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 1211   | 20         | AS6 position% |                | Position% if AS6 condition is position >=% or <=%  |
| 1221   | Make       | AS6 contact   |                | Make, break  |

Table 12. AS7 Relay

| Obj n° | Value      | Function      | Actuator Setup   |
|--------|------------|---------------|--|
|        |            |               | Description  |
| 1202   | Open limit | AS7 condition | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 1212   | 20         | AS7 position% | Position% if AS7 condition is position >=% or <=%  |
| 1222   | Make       | AS7 contact   | Make, break  |

Table 13. AS8 Relay

| Obj n° | Value      | Function      | Actuator Setup   |
|--------|------------|---------------|--|
|        |            |               | Description  |
| 1203   | Open limit | AS8 condition | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 1213   | 20         | AS8 position% | Position% if AS8 condition is position >=% or <=%  |
| 1223   | Make       | AS8 contact   | Make, break  |

Table 14. AS9 Relay

| Obj n° | Value      | Function      | Actuator Setup   |
|--------|------------|---------------|--|
|        |            |               | Description  |
| 1204   | Open limit | AS9 condition | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 1214   | 20         | AS9 position% | Position% if AS9 condition is position >=% or <=%  |
| 1224   | Make       | AS9 contact   | Make, break  |

Table 15. AS10 Relay

| Obj n° | Value      | Function       | Actuator Setup |  |
|--------|------------|----------------|----------------|--|
|        |            |                | Description    |  |
| 1205   | Open limit | AS10 condition |                | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 1215   | 20         | AS10 position% |                | Position% if AS10 condition is position >=% or <=%   |
| 1225   | Make       | AS10 contact   |                | Make, break  |

Table 16. AS11 Relay

| Obj n° | Value      | Function       | Actuator Setup |  |
|--------|------------|----------------|----------------|--|
|        |            |                | Description    |  |
| 1206   | Open limit | AS11 condition |                | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 1216   | 20         | AS11 position% |                | Position% if AS11 condition is position >=% or <=%   |
| 1226   | Make       | AS11 contact   |                | Make, break  |

Table 17. 2-Speed Timer

| Obj n° | Value | Function                  | Actuator Setup |   |
|--------|-------|---------------------------|----------------|---|
|        |       |                           | Description    |   |
| 51     | Off   | Status                    |                | Off=disable timer in CL, on=enable                          |
| 55     | 2     | On time in closing        |                | From 2 to 200   |
| 56     | 2     | Off time in closing       |                | From 2 to 200   |
| 53     | 0     | Start position in closing |                | % of position where timer operation starts<br>From 0 to 100 |
| 54     | 100   | Stop position in closing  |                | % of position where timer operation ends<br>From 0 to 100   |
| 52     | Off   | Status                    |                | Off=disable timer in OP, on=enable                          |
| 59     | 2     | On time in opening        |                | From 2 to 200   |
| 60     | 2     | Off time in opening       |                | From 2 to 200   |
| 57     | 0     | Start position in opening |                | % of position where timer operation starts<br>From 0 to 100 |
| 58     | 100   | Stop position in opening  |                | % of position where timer operation ends<br>From 0 to 100   |

**Table 18. Miscellaneous**

| Actuator Setup |          |                   |                             |
|----------------|----------|-------------------|-----------------------------|
| Obj n°         | Value    | Function          | Description                 |
| 531            | Standard | Torque mode       | Standard, 3 points          |
| 103            | Absent   | Alkaline battery  | Present, absent             |
| 6              | 1.01.01  | Present date      | Present date, dd.mm.yy      |
| 7              | 0.00.00  | Present time      | Present time, hh.mm.ss      |
| 507            | 20       | Torque bypass     | From 0 to 20, % of position |
| 144            | 100      | Jammed valve time | From 0 to 100 seconds       |
| 235            | Enabled  | Bluetooth         | Enabled, disabled           |

**Table 19. Fail Safe**

| Actuator Setup |       |          |   |
|----------------|-------|----------|---|
| Obj n°         | Value | Function | Description   |
| 715            | Off   | Action   | Off, close, open, stay put, go to position %                          |
| 717            | 10    | Delay    | Delay before than fail action takes place, from 0 to 255 seconds      |
| 716            | 50    | Position | Position % of failsafe if action is "go to position %", from 0 to 100 |

**Table 20. Interlocks**

| Actuator Setup |       |                      |                      |
|----------------|-------|----------------------|----------------------|
| Obj n°         | Value | Function             | Description          |
| 708            | Off   | Interlock in opening | Absent, present, off |
| 709            | Off   | Interlock in closing | Absent, present, off |

**Table 21. Positioner**

| Actuator Setup |           |                             |   |
|----------------|-----------|-----------------------------|---|
| Obj n°         | Value     | Function                    | Description                                   |
| 710            | 0.5       | Dead band                   | From "position resolution" to 25.5%           |
| 711            | 6         | Motion inhibit              | Motion inhibit time in seconds, from 1 to 255 |
| 712            | 0         | % min                       | Standard 0                                    |
| 713            | 100       | % max                       | Standard 100                                  |
| 701            | 4 mA = CL | Polarity of input 4 - 20 mA | 4 mA = CL, 20 mA = OP                         |

**Table 22. Out 4 - 20 mA**

| Actuator Setup |           |                              |                        |
|----------------|-----------|------------------------------|------------------------|
| Obj n°         | Value     | Function                     | Description            |
| 702            | 4 mA = CL | Polarity of output 4 - 20 mA | 4 mA = CL, 20 mA = OP  |
| 718            | Position  | Output signal                | Position mA, torque mA |

**Table 23. Bus Control**

|        |            |                                 | Actuator Setup   |  |
|--------|------------|---------------------------------|--|--|
| Obj n° | Value      | Function                        | Description  |  |
| 408    | Off        | Status of termination channel 1 | Off, On  |  |
| 409    | Off        | Status of termination channel 2 | Off, On  |  |
| 419    | Auto       | Mode                            | Channel_1, Channel_2, auto   |  |
| 418    | Auto       | Modbus baud rate                | Auto, 600, 1200, 2400, 4800, 9600, 19200, 38400  |  |
| 406    | One        | Modbus parity                   | None, even, odd  |  |
| 407    | 1          | Modbus node                     | Modbus address, from 0 to 246  |  |
| 423    | 1          | Profibus node                   | Profibus address, from 1 to 126  |  |
| 400    | Open limit | DIN 1                           | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |  |
| 401    | Open limit | DIN 2                           | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |  |
| 402    | Open limit | DIN 3                           | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |  |
| 403    | Open limit | DIN 4                           | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |  |
| 404    | Open limit | DIN 5                           | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |  |

| Obj n° | Value      | Function                   | Actuator Setup |  |
|--------|------------|----------------------------|----------------|--|
|        |            |                            | Description    |  |
| 405    | Open limit | DIN 6                      |                | Open limit, close limit, position >=%, position <=%, closing, opening, running, blinker, mid-travel, local selected, remote selected, local stop on, ESD/PST-efs, manual operation (handwheel), motor over temperature alarm, over torque alarm, over torque alarm in OP, over torque alarm in CL, valve jammed alarm in OP, valve jammed alarm in CL, valve jammed alarm, low battery alarm, warnings, mid travel alarms, EFS in manual, PST failed, Mains only As8, EFS mid-travel, INTER/PST-icon, EFS coil OFF |
| 411    | 50         | DIN 1 pos%                 |                | Position% if DIN 1 = position >= or <=   |
| 412    | 50         | DIN 2 pos%                 |                | Position% if DIN 2 = position >= or <=   |
| 413    | 50         | DIN 3 pos%                 |                | Position% if DIN 3 = position >= or <=   |
| 414    | 50         | DIN 4 pos%                 |                | Position% if DIN 4 = position >= or <=   |
| 415    | 50         | DIN 5 pos%                 |                | Position% if DIN 5 = position >= or <=   |
| 416    | 50         | DIN 6 pos%                 |                | Position% if DIN 6 = position >= or <=   |
| 417    | 1          | Hart node                  |                | Hart address, from 0 to 63   |
| 428    | 1          | Profibus redundant node    |                | Profibus address of backup slave, from 1 to 126  |
| 425    | 1          | Hart device number         |                | Hart serial number from 0 to 116777200, 3 bytes  |
| 426    | 0          | Hart configuration changes |                | Number of Hart configuration changes, visible only from node report menu   |

**Table 24. Restricted**

| Obj n° | Value                   | Function               | Actuator Setup |  |
|--------|-------------------------|------------------------|----------------|--|
|        |                         |                        | Description    |  |
| 160    | 1.2                     | Speed bypass           |                | Speed bypass time. Set value from 0 to 25.5 (standard >1)                                |
| 508    | 5                       | Torque stop zone       |                | Torque stop zone in % of position, from 0 to 20% in OP (or 100 to 80% in CL)             |
| 115    | 1 (ICON-EFS)<br>4 (F01) | Direction test         |                | Direction test (F01), from 0 to 255 (standard 4), for ICON/EFS standard 1                |
| 145    | 400                     | Voltage span           |                | Voltage span, from 0 to 1000 (change at least 1 V to enter new value)                    |
| 107    | Off                     | 1 P.man                |                | Disabled, enabled  |
| 116    | Base                    | Hardware configuration |                | Base, lonworks, modbus, profibus-DPV0, modbus_m, FF, hart, profibus-DPV1, profibus-DPV1r |
| 700    | Disabled                | Positioner             |                | Disabled, enabled  |
| 704    | 4 - 20 mA               | Position request type  |                | From 4 - 20 mA input or from bus   |
| 703    | Disabled                | Failsafe enable        |                | Disabled, enabled  |
| 421    | Torque                  | Bus An. Out.           |                | Torque, torque + temperature (only FF)   |
| 706    | Absent                  | Ain/Aout card enable   |                | Present, absent  |
| 705    | Disable                 | EXT "Bluetooth" enable |                | Enable, disable  |
| 719    | Disable                 | IrDA enable            |                | Enable, disable  |
| 410    | I24                     | Bus card protocol      |                | Communication protocol among base and bus cards, I20 or I24                              |
| 422    | Disable                 | PID (not available)    |                | Disable, enable (always disabled)  |

Table 25. Reserved

| Obj n° | Value    | Function                        | Actuator Setup |   |
|--------|----------|---------------------------------|----------------|---|
|        |          |                                 |                | Description   |
| 148    | Icon     | SW type                         |                | ICON, F01   |
| 173    | I24 V4   | Terminal board type             |                | I24 V4, 5 relays, 8/9 relays, 12 relays, I24 Gold PR                                  |
| 105    | Mask     | Additional variables            |                | Mask, view  |
| 4      | Auto     | Backlight                       |                | Auto, on  |
| 134    | 1.5      | Reversal delay                  |                | Reversal delay, from 0 to 5.5 seconds (standard > 1)                                  |
| 146    | 200      | Volt span bit                   |                | Voltage span in bit, can only be read   |
| 720    | 650      | 4 mA in                         |                | Bit corresponding to 4 mA input   |
| 721    | 3500     | 20 mA in                        |                | Bit corresponding to 20 mA input  |
| 722    | 650      | 4 mA out                        |                | Bit corresponding to 4 mA output  |
| 723    | 3500     | 20 mA out                       |                | bit corresponding to 20 mA output   |
| 161    | 451      | Curr sens 2 A                   |                | Bits when current is 2 A  |
| 162    | 382      | Curr sens 3.5 A                 |                | Bits when current is 3.5 A  |
| 163    | 387      | Curr sens 7 A                   |                | Bits when current is 7 A  |
| 164    | 443      | Curr sens 15 A                  |                | Bits when current is 15 A   |
| 165    | 441      | Curr sens 30 A                  |                | Bits when current is 30 A   |
| 424    | 10       | Speed filter                    |                | From 0 to 255   |
| 170    | 1        | Base heater reference           |                | °C reference of heater on base card, from -40 to 50 °C                                |
| 171    | -2       | LCD heater reference            |                | °C reference of heater on display card, from -40 to 50 °C                             |
| 172    | -1       | Terminal board heater reference |                | °C reference of heater on terminal board, from -40 to 50 °C                           |
| 707    | Disable  | Sleep mode                      |                | Enable, disable SLEEP function  |
| 238    | Off      | MR in SLEEP                     |                | On/off of monitor relay in sleep mode   |
| 576    | Standard | Torque function                 |                | Mode to evaluate torque, standard or advanced   |
| 533    | Standard | Interlock mode                  |                | Standard or advanced (local+interlock OP/CL)  |
| 420    | Disable  | New FW                          |                | Disable or enable, set to "enable" to download a new firmware                         |
| 429    | Disable  | Serial cmd                      |                | Disable or enable OP/CL/ST commands by BLT or serial RS232                            |
| 430    | Disable  | Loc/Rem                         |                | Enable or disable "Local + Remote" control mode                                       |
| 431    | s/n°     | Bluetooth code                  |                | Select Bluetooth code or valve tag  |
| 815    | 75       | EFS-duty %                      |                | Duty of EFS clutch (used only in EFS actuator)<br>Not used for ICON3000               |
| 803    | Close    | Spring action                   |                | Actuator movement under   |
| 804    | On       | EFS electrical cmd              |                | Enable/disable of electrical cmd in direction of safe action<br>Not used for ICON3000 |
| 805    | PST      | ESD input mode                  |                | Selector of ESD input of actuator, PST or EFS (electrical cmd). Not used for ICON3000 |
| 806    | Absent   | EFS signal type                 |                | Option Absent/present in case of ESD input used as EFS cmd. Not used for ICON3000     |
| 133    | 0        | CMD-Filter                      |                | From 0 to 30 filter of OP/CL/ST commands signals                                      |
| 135    | 0        | ESD-INT Filter                  |                | From 0 to 30 filter of ESD/INT commands signal  |

Table 26. Serial Number

| Nameplate |              |               |                    |
|-----------|--------------|---------------|--------------------|
| Obj n°    | Value        | Function      | Description        |
| 300       | 031234E01003 | Serial number | Max. 12 characters |

Table 27. Actuator Size

| Nameplate |                |               |                    |
|-----------|----------------|---------------|--------------------|
| Obj n°    | Value          | Function      | Description        |
| 301       | ICON-010-40-90 | Actuator size | Max. 28 characters |

Table 28. Wiring Diagram

| Nameplate |              |                |                    |
|-----------|--------------|----------------|--------------------|
| Obj n°    | Value        | Function       | Description        |
| 302       | WD-80-AT-000 | Wiring diagram | Max. 28 characters |

Table 29. Enclosure

| Nameplate |           |           |                    |
|-----------|-----------|-----------|--------------------|
| Obj n°    | Value     | Function  | Description        |
| 303       | Eex-d-IIC | Enclosure | Max. 28 characters |

Table 30. Certificate

| Nameplate |       |             |                    |
|-----------|-------|-------------|--------------------|
| Obj n°    | Value | Function    | Description        |
| 304       | ATEX  | Certificate | Max. 28 characters |

Table 31. Lubricant

| Nameplate |              |           |                    |
|-----------|--------------|-----------|--------------------|
| Obj n°    | Value        | Function  | Description        |
| 305       | SHELL_TIVELA | Lubricant | Max. 28 characters |

Table 32. Torque / Thrust

| Nameplate |       |                                 |                    |
|-----------|-------|---------------------------------|--------------------|
| Obj n°    | Value | Function                        | Description        |
| 532       | Nm    | Torque, thrust engineering unit | ft-lbf, Nm, lb, KN |
| 307       | 90    | Torque, thrust nominal value    | Max. 28 characters |

Table 33. Actuator Speed

| Nameplate |       |                                 |                                    |
|-----------|-------|---------------------------------|------------------------------------|
| Obj n°    | Value | Function                        | Description                        |
| 132       | RPM   | Actuator speed engineering unit | s/90°, RPM, mm/s, in/s             |
| 308       | 48    | Actuator speed value            | Actuator speed, max. 28 characters |

**Table 34. Power Supply**

| Obj n° | Value | Function                 | Nameplate                    |
|--------|-------|--------------------------|------------------------------|
|        |       |                          | Description                  |
| 111    | AC3ph | Power type               | AC3ph, AC1ph, DC             |
| 110    | 400   | Supply voltage value     | Nominal voltage supply value |
| 104    | 50 Hz | Supply voltage frequency | 50 Hz, 60 Hz                 |

**Table 35. Motor Data**

| Obj n° | Value      | Function                                    | Nameplate   |
|--------|------------|---|---|
|        |            |   | Description   |
| 113    | AC3ph      | Motor supply type                           | AC3ph, AC1ph, DC  |
| 122    | 0.5        | Motor nominal power (rating)                | KW, from 0 to 99.9  |
| 123    | 0.3        | Motor current In<br>(motor nominal current) | A, from 0 to 99.9   |
| 124    | 0.4        | Motor current Is<br>(seating current)       | A, from 0 to 99.9   |
| 125    | 0.5        | Motor current Icc<br>(locked rotor current) | A, from 0 to 999.9  |
| 126    | S2-15 min. | Motor service                               | S2-15 min., S4-25%-60start/h, S4-25%-200start/h,<br>S4-25%-600start/h, S4-25%-1200start/h,<br>S4-25%-3600start/h, S9 continuous |
| 112    | 6          | Motor poles                                 | From 0 to 32  |
| 427    | SM32       | Motor code                                  | Max. 28 characters  |
| 577    | 10         | Gears ratio                                 | Reduction ratio of gears, from 1 to 1000  |

**Table 36. Test Date**

| Obj n° | Value    | Function  | Nameplate                     |
|--------|----------|-----------|-------------------------------|
|        |          |           | Description                   |
| 306    | 17.04.04 | Test date | Factory test date, (dd.mm.yy) |

**Table 37. Revision**

| Obj n° | Value | Function    | Nameplate   |
|--------|-------|-------------|---|
|        |       |             | Description   |
| 114    | 4     | HW revision | Hardware revision   |
| 5      | 2.03  | SW H8       | Software revision H8 base card, read only from ICON firmware  |
| 8      | 1.10  | SW PIC      | Software revision PIC base card, read only from ICON firmware |

**Table 38. Torque Sensor**

| Obj n° | Value | Function             | Nameplate   |
|--------|-------|----------------------|---|
|        |       |                      | Description   |
| 536    | 700   | F01tor op 100%       | Value of potentiometer at 100% of opening torque, in F01. Not used for ICON3000 |
| 537    | 600   | F01tor op 50%        | Value of potentiometer at 50% of opening torque, in F01. Not used for ICON3000  |
| 538    | 400   | F01tor op 50%        | Value of potentiometer at 50% of closing torque, in F01. Not used for ICON3000  |
| 539    | 300   | F01tor op 100%       | Value of potentiometer at 100% of closing torque, in F01. Not used for ICON3000 |
| 540    | 500   | I2tor op 0% +5%      | Opening speed with torque 0% and voltage +5% of nominal                         |
| 541    | 450   | I2tor op 40% +5%     | Opening speed with torque 40% and voltage +5% of nominal                        |
| 542    | 400   | I2tor op 70% +5%     | Opening speed with torque 70% and voltage +5% of nominal                        |
| 543    | 300   | I2tor op 100% +5%    | Opening speed with torque 100% and voltage +5% of nominal                       |
| 577    | 10    | Gears ratio          | Reduction ratio of gears, from 1 to 1000  |
| 545    | 440   | I2tor op 40% -5%     | Opening speed with torque 40% and voltage -5% of nominal                        |
| 546    | 390   | I2tor op 70% -5%     | Opening speed with torque 70% and voltage -5% of nominal                        |
| 547    | 290   | I2tor op 100% -5%    | Opening speed with torque 100% and voltage -5% of nominal                       |
| 548    | 600   | I2tor cl 0% +5%      | Closing speed with torque 0% and voltage +5% of nominal                         |
| 549    | 550   | I2tor cl 40% +5%     | Closing speed with torque 40% and voltage +5% of nominal                        |
| 550    | 500   | I2tor cl 70% +5%     | Closing speed with torque 70% and voltage +5% of nominal                        |
| 551    | 450   | I2tor cl 100% +5%    | Closing speed with torque 100% and voltage +5% of nominal                       |
| 553    | 540   | I2tor cl 40% -5%     | Closing speed with torque 40% and voltage -5% of nominal                        |
| 554    | 490   | I2tor cl 70% -5%     | Closing speed with torque 70% and voltage -5% of nominal                        |
| 555    | 430   | I2tor cl 100% -5%    | Closing speed with torque 100% and voltage -5% of nominal                       |
| 580    | 400   | I2tor voltage        | Voltage of torque calibration, from 0 to 1000 V                                 |
| 106    | 50 Hz | I2tor freq.          | 50 Hz, 60 Hz, frequency of torque calibration                                   |
| 509    | 2     | I2tor Ktemp          | Temperature compensation, from 1 to 20  |
| 994    | 70    | Torque-set CL (ICON) | Value of torque set in factory  |
| 995    | 70    | Torque-set OP (ICON) | Value of torque set in factory  |
| 996    | 70    | Torque-set CL (F01)  | Value of torque set in factory. Not used for ICON3000                           |
| 997    | 70    | Torque-set OP (F01)  | Value of torque set in factory. Not used for ICON3000                           |

**Table 39.**

| Obj n° | Value | Function            | Valve Data  |
|--------|-------|---------------------|---|
|        |       |                     | Description   |
| 154    | f5000 | Valve tag name      | Max. 28 characters  |
| 156    | q234f | Valve serial number | Max. 28 characters  |
| 990    | -     | Manufacturer        | Max. 28 characters  |
| 991    | -     | Break-OP torque     | Max. 28 characters  |
| 992    | -     | Max. stem thrust    | Max. 28 characters  |
| 993    | -     | Flange type         | Max. 28 characters  |
| 542    | 400   | I2tor op 70% +5%    | Opening speed with torque 70% and voltage +5% of nominal  |
| 543    | 300   | I2tor op 100% +5%   | Opening speed with torque 100% and voltage +5% of nominal |
| 996    | 70    | Torque-set CL (F01) | Value of torque set in factory. Not used for ICON3000     |
| 997    | 70    | Torque-set OP (F01) | Value of torque set in factory. Not used for ICON3000     |

**Operation Log**

**Table 40. General Log**

| Obj n° | Value | Function                        | Maintenance               |
|--------|-------|---------------------------------|---------------------------|
|        |       |                                 | Description               |
| 924    | 10    | Opening time                    | Seconds, Read-only        |
| 925    | 10    | Closing time                    | Seconds, Read-only        |
| 920    | 1200  | Contacteur cycles               | Resolution 100, Read-only |
| 922    | 1020  | Motor run time                  | Hours, Read-only          |
| 928    | 300   | No power time                   | Hours, Read-only          |
| 926    | 13    | Utilization rate                | %, Read-only              |
| 956    | -30   | Min. temperature                | °C, Read-only             |
| 957    | 70    | Max. temperature                | °C, Read-only             |
| 958    | -34   | Min. terminal board temperature | °C, Read-only             |
| 959    | 72    | Max. terminal board temperature | °C, Read-only             |
| 961    | 80    | Max. motor temperature          | °C, Read-only             |
| 964    | 2     | Motor thermostat alarms         | Read-only                 |
| 965    | 2     | Torque alarms                   | Read-only                 |

**Table 41. Recent Log**

| Obj n° | Value | Function                       | Maintenance               |
|--------|-------|--------------------------------|---------------------------|
|        |       |                                | Description               |
| 921    | 0     | Recent contacteur cycles       | Resolution 100, Read-only |
| 923    | 0     | Recent motor run time          | Hours, Read-only          |
| 929    | 0     | Recent no power time           | Seconds, Read-only        |
| 927    | 0     | Recent utilization rate        | %, Read-only              |
| 950    | 0     | Recent min temperature         | °C, Read-only             |
| 951    | 0     | Recent max temperature         | °C, Read-only             |
| 952    | 0     | Recent min term. board temper. | °C, Read-only             |
| 953    | 0     | Recent max term. board temper. | °C, Read-only             |
| 955    | 0     | Recent max motor temperature   | °C, Read-only             |
| 962    | 0     | Recent motor thermostat alarms | Read-only                 |
| 963    | 0     | Recent torque alarms           | Read-only                 |
| 964    | 2     | Motor thermostat alarms        | Read-only                 |
| 965    | 2     | Torque alarms                  | Read-only                 |

**Table 42. Torque Profile**

| Maintenance |         |                                   |             |
|-------------|---------|-----------------------------------|-------------|
| Obj n°      | Value   | Function                          | Description |
| 568         | 50      | Breakout in opening               | Read-only   |
| 570         | 50      | Peak run in opening               | Read-only   |
| 572         | 50      | Ending in opening                 | Read-only   |
| 574         | 1.01.00 | Op. torque profile date           | Read-only   |
| 560         | 50      | Breakout in closing               | Read-only   |
| 562         | 50      | Peak run in closing               | Read-only   |
| 564         | 50      | Ending in closing                 | Read-only   |
| 566         | 1.01.00 | Cl. torque profile date           | Read-only   |
| 569         | 50      | Reference breakout in op.         | Read-only   |
| 571         | 50      | Reference peak run in op.         | Read-only   |
| 573         | 50      | Reference ending in op.           | Read-only   |
| 575         | 1.01.00 | Reference op. torque profile date | Read-only   |
| 561         | 50      | Reference breakout in cl.         | Read-only   |
| 563         | 50      | Reference peak run in cl.         | Read-only   |
| 565         | 50      | Reference ending in cl.           | Read-only   |
| 567         | 1.01.00 | Reference cl. torque profile date | Read-only   |

**Alarm Log**

**Table 43. Alarms**

| Maintenance |                   |                       |                            |
|-------------|-------------------|-----------------------|----------------------------|
| Obj n°      | Value             | Function              | Description                |
| 900         | 1.1.01_00.00.00_0 | Alarm 0               | Alarm register 0           |
| 901         | 1.1.01_00.00.00_0 | Alarm 1               | Alarm register 1           |
| 902         | 1.1.01_00.00.00_0 | Alarm 2               | alarm register 2           |
| 903         | 1.1.01_00.00.00_0 | Alarm 3               | Alarm register 3           |
| 904         | 1.1.01_00.00.00_0 | Alarm 4               | Alarm register 4           |
| 905         | 0                 | Oldest alarm register | Obj number of oldest alarm |

**Note:** In the FW version > 5.50, ALARM LOG is read by the obj -251, -252, -253, -255.

**Table 44. Warnings**

| Maintenance |                   |                         |                              |
|-------------|-------------------|-------------------------|------------------------------|
| Obj n°      | Value             | Function                | Description                  |
| 910         | 1.1.01_00.00.00_0 | Warning 0               | Warning 0 register           |
| 911         | 1.1.01_00.00.00_0 | Warning 1               | Warning 1 register           |
| 912         | 1.1.01_00.00.00_0 | Warning 2               | Warning 2 register           |
| 913         | 1.1.01_00.00.00_0 | Warning 3               | Warning 3 register           |
| 914         | 1.1.01_00.00.00_0 | Warning 4               | Warning 4 register           |
| 915         | 0                 | Oldest warning register | Obj number of oldest warning |

**Note:** In the FW version > 5.50, ALARM LOG is read by the obj -255, -256, -257, -258.

**Table 45. Maintenance Date**

| Maintenance |                   |                         |   |
|-------------|-------------------|-------------------------|---|
| Obj n°      | Value             | Function                | Description   |
| 151         | 19.04.04          | Last date               | dd.mm.yy  |
| 152         | 0,043506944       | Next date               | dd.mm.yy  |
| 309         | 17.014.04         | Start-up date           | dd.mm.yy  |
| 310         | 1.01.02           | Recent log date         | Date of the last "clear recent log" that is: start date of the recent log registers |
| 914         | 1.1.01_00.00.00_0 | Warning 4               | Warning 4 register  |
| 915         | 0                 | Oldest warning register | Obj number of oldest warning  |

**Table 46. Only Read**

| Maintenance |         |          |   |
|-------------|---------|----------|---|
| Obj n°      | Value   | Function | Description   |
| 14          | 1       | Identity | 4 characters = ICON, F01b, 4 characters = 4/20, base, 11Rb, 4 characters = language = efsi, epsi, from firmware |
| 9999        | -       | CRC      | Eeprom memory error   |
| 150         | 0       | Password | Password  |
| 141         | English | Language | English, Italiano, Espanol, Portugues, Italiana, Francais, etc.   |

## Section 5: Alarm "Hardware n°"

If the diagnostic program of the ICON3000 detects a malfunction in any of the hardware modules, a HARDWARE n° alarm is generated (refer to the ICON3000 IOM; Diagnostic Messages).

The number "n°" indicates the module that is not working. The problem may be due to malfunction of a module, incorrect wiring between modules, or an incorrect setting.

The following hardware alarms can be detected:

### Hardware 1

- Incorrect coding of local push-buttons and selector.  
The base card detects the status of the local push-buttons and selector via 5 Hall effect sensors. Four magnets, located on the cover of the local operator interface, provide the magnetic field to the sensor. The alarm may be attributable to incorrect positioning of magnets in the cover.

### Hardware 2

- Incorrect configuration of the "Ain/Aout" optional module.

### Hardware 3

- No communication between the "Ain/Aout" and "base" cards.  
Turn off the power and check that the base card is equipped with the "Ain/Aout" optional card. Cycle power on the actuator, observe the first message that appears on the display, and then check the following parameters in the "RESTRICTED" menu routines:

- Term board: should be set to "I24 V4."
- Card Ain/Aout: should be set to "PRESENT."

If the settings are incorrect, enter the correct values and then a cycle power on the actuator. If the settings are correct, check the base card and the optional module "Ain/Aout."

### Hardware 4

- Incorrect configuration of type of terminal board.

### Hardware 5

- No communication between the terminal board and base card.  
Turn off the power and check the base card to see if it is equipped with the "Ain/Aout" or "TERMINAL BOARD ADAPTOR" card. Cycle power on the actuator and check the following parameters in the "RESTRICTED" menu routines:

- Term board: should be set to "I24 V4."
- Card Ain/Aout: should be set to "PRESENT" if the "Ain/Aout" card is present and should be set to "ABSENT" if the "TERMINAL BOARD ADAPTOR" card is present. In the latter case check also that the 5 dip-switches on the card are in the "open" position.

If the settings are wrong, enter the correct values and then proceed to cycle power on the actuator. If the settings are correct, check the base card, the "Ain/Aout" or "TERMINAL BOARD ADAPTOR" cards, the terminal board, and the wiring between the terminal board and base card (see Section 6: Terminal Board Types).

### Hardware 6

- Incorrect configuration of actuator type "ICON."  
This alarm is generated when:
  - The parameter "SW type" in the "RESTRICTED" menu is set to "ICON," but the "POTENTIOMETER" card is present on the base card.

### Hardware 7

- Incorrect configuration of type of bus card.

#### Hardware 8

- No communication between the bus card and base card.  
Turn off the power and check that the base card is equipped with the correct bus interface card. Cycle power on the actuator and check the following parameters in the "RESTRICTED" menu routines:
  - HW config: should be set to the "option" corresponding to the bus interface present on the base card.
  - Bus protocol: should be set to "I24" or "I20" according to the relevant bus protocol instruction manual.

#### Hardware 9

- Reserved. Not used for ICON3000.

#### Hardware 10

- Reserved. Not used for ICON3000.

#### Hardware 11

- No communication between the bus (Profibus redundant card) and logic card. Turn off the power and check that the base card is equipped with the correct bus interface card. Cycle power on the actuator and check the following parameters in the "RESTRICTED" menu routines:
  - HW config: should be set to the "option" corresponding to the bus interface present on the base card.
  - Bus protocol: should be set to "I24" or "I20" according to the relevant bus protocol instruction manual.

#### Hardware 12

- No communication between the encoder and logic card.  
Turn off the power and check the encoder cable; if damaged, it must be replaced. Cycle power on the actuator to check if the problem is corrected.  
If the problem is not corrected, replace the Encoder. Cycle power on the actuator to check if the problem is resolved.  
If the problem is still not corrected, replace the Logic Card. Cycle power on the actuator to check if the problem is resolved.

#### Hardware 13

- Encoder damaged or incorrectly configured.  
Turn off the power and check the mechanical condition of the encoder. If damaged, it must be replaced. Cycle power on the actuator to check if the problem is corrected.  
If the problem still not corrected, replace the Logic Card. Cycle power on the actuator to check if the problem is resolved.

## Section 6: Terminal Board Types

The features of the ICON3000 terminal board are described in the the ICON3000 IOM. If the ICON3000 has a 4 - 20 mA analog input and output, the optional card “Ain/Aout” is plugged onto the base card in place of the “TERMINAL BOARD ADAPTOR” card.

The following settings should be performed in the “RESTRICTED” menu routines:

- Term board: set to “I24 V4.”
- Card Ain/Aout: set to “PRESENT” if the card “Ain/Aout” is plugged onto the base card, or set to “ABSENT” if instead the “TERMINAL BOARD ADAPTOR” card is installed. The 5 dip-switches on the TERMINAL BOARD ADAPTOR card should be set to “open” (OFF).

Figure 4 ICON3000 Terminal Board Cards

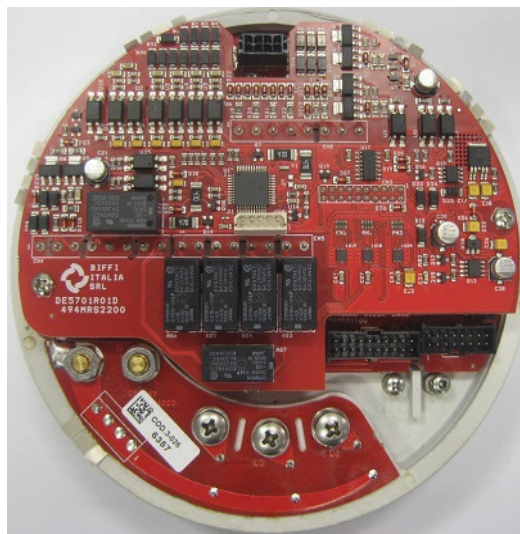
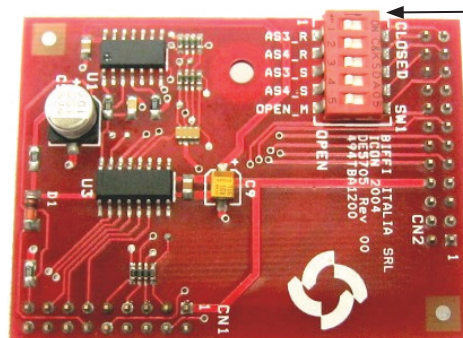


Figure 5



Dip-switches on the Terminal Board Adaptor (TBA) card

## 6.1 Terminal Board Adaptor (TBA) Card

This is an optional module of the ICON3000 base card.

The “TERMINAL BOARD ADAPTOR” card is present as standard. The 5 dip-switches on the “TERMINAL BOARD ADAPTOR” card must be placed in the “open” position. If the “Ain/Aout” optional module is required, the “TERMINAL BOARD ADAPTOR” card is removed from base card and the “Ain/Aout” card is mounted in the same position.

Figure 6 Ain/Aout card

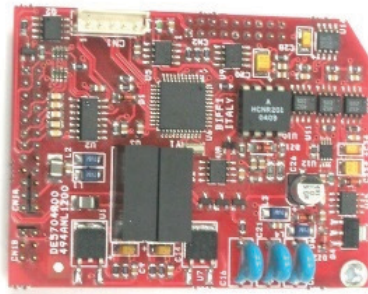


Figure 7 Terminal Board Adaptor card

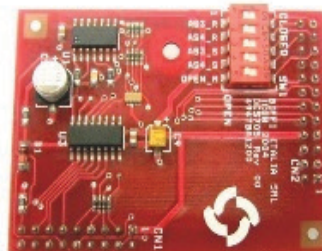
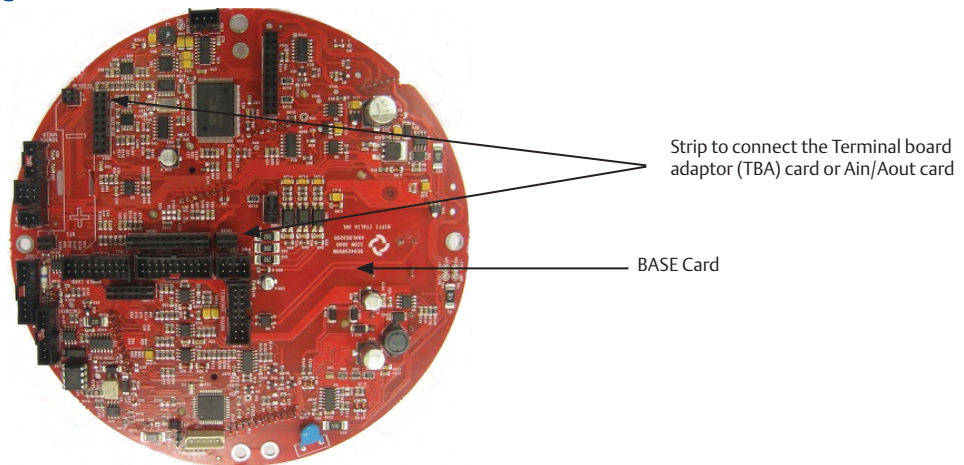


Figure 8



## Section 7: Configuration

ICON3000 configuration and firmware upgrades can be performed via wired connection to RS232 service serial port or via Bluetooth™ wireless connection.

The tools that can be used to perform the mentioned above functions are:

- A-Manager
- DCMLink

Refer to the specific IOM for the dedicated guide.

## Section 8: Test Point and Connector Base Card

Figure 9

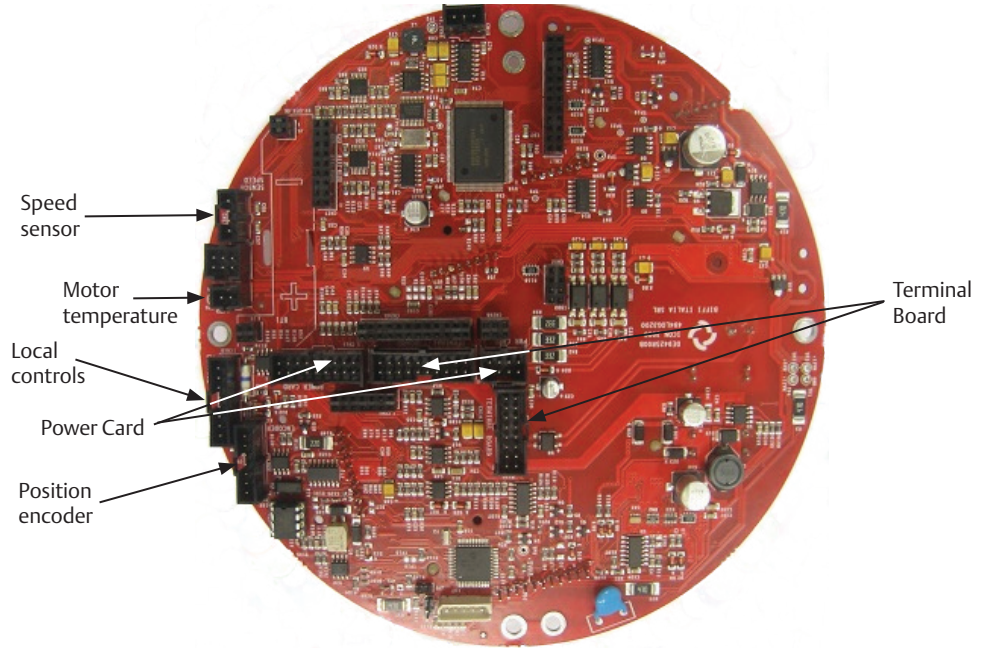
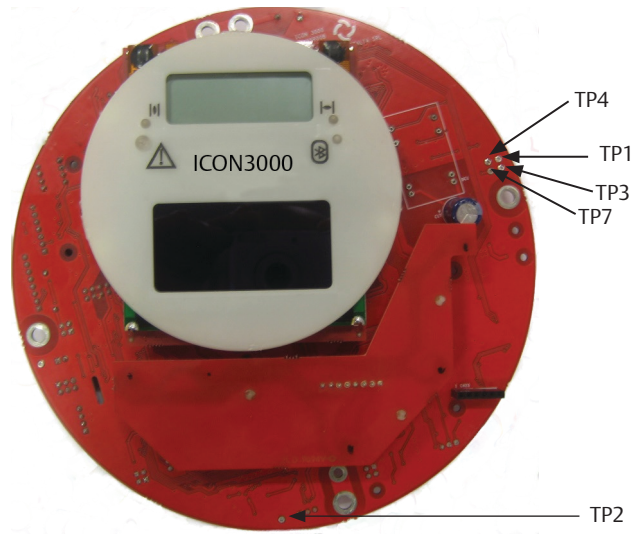


Figure 10

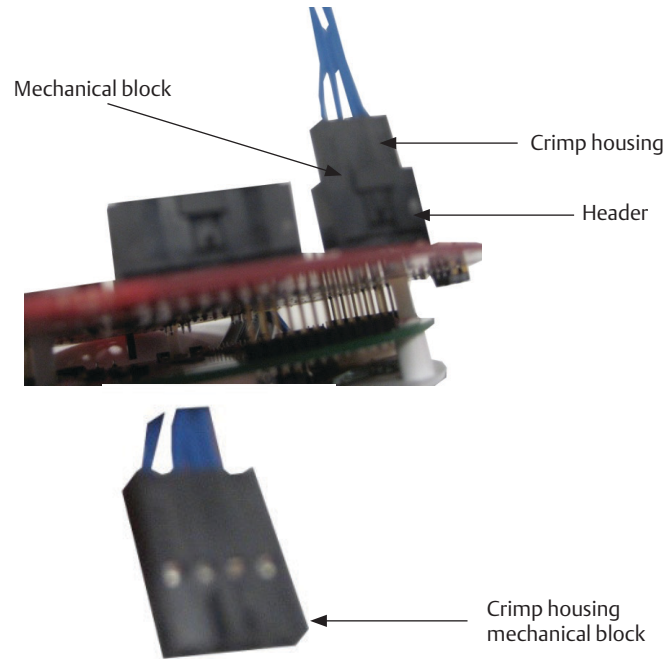


Test Points:

- TP1: 0 Vm
- TP2: 3.3 Vh8
- TP3: 13 Vm
- TP4: 12 Vm (in case of power supply by DC/DC converter)
- TP7: 5 Vm

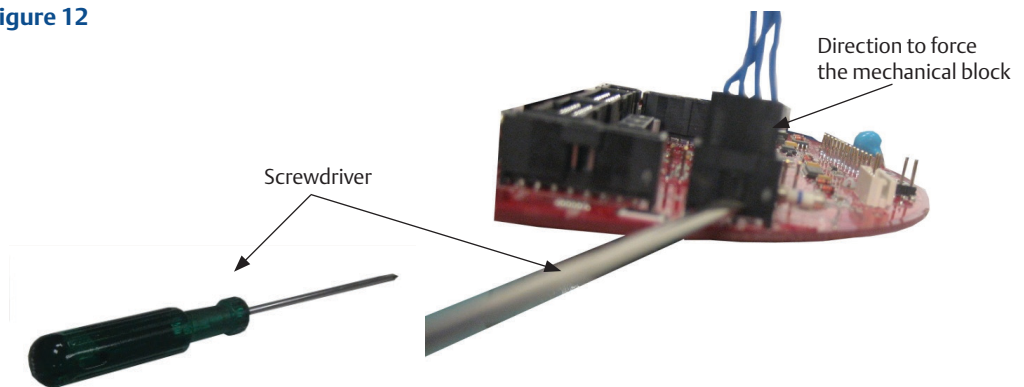
The connector is composed of two pieces: header and crimp housing. The header is welded to the printed circuit board and the crimp housing is connected to wires. The mechanical block (see Figure 11) part of the crimp housing can complicate the disconnection of the crimp housing from the header, which if done without due care can potentially result in damage to the connector and/or wires.

Figure 11



Disconnection of the header and crimp housing can be facilitated with a screwdriver. Use the screwdriver to force the mechanical block in the direction indicated in Figure 12 below until the crimp housing becomes free from the header.

Figure 12



## Section 9: Firmware of DE9425 HW REV $\geq$ 00B

BASE card DE 5703 HW rev  $\geq$  04 works only with:

- FW H8S rev  $\geq$  9.00
- FW PIC rev  $\geq$  8.00

*This page is intentionally left blank*

Biffi Italia s.r.l.  
Strada Biffi 165  
29017 Fiorenzuola d'Arda (PC)  
Italy  
T +39 0523 944 411

For complete list of sales and manufacturing sites, please visit  
[www.biffi.it](http://www.biffi.it) or contact us at [biffi\\_italia@biffi.it](mailto:biffi_italia@biffi.it)

VCIOM-16329-EN ©2021 Biffi. All rights reserved.

The contents of this publication are presented for information purposes only, and while every effort has been made to ensure their accuracy, they are not to be construed as warranties or guarantees, express or implied, regarding the products or services described herein or their use or applicability. All sales are governed by our terms and conditions, which are available on request. We reserve the right to modify or improve the designs or specifications of our products at any time without notice.

